

LPMS-IG1

LPMS Low-Drift, Low-Noise Inertial Measurement Unit (IMU) with CAN Bus / RS232 Connectivity

The LPMS-IG1 is a 9-axis inertial measurement unit (IMU) offering high precision orientation and linear acceleration measurements in an IP67-rated enclosure. It is equipped with a powerful central processing unit fusing raw data from gyroscope, accelerometer, magnetometer to calculate results on the fly with low drift and high accuracy. LPMS-IG1 perfectly fits application cases in an industrial environment where motion measurements with high precision and low latency are required.



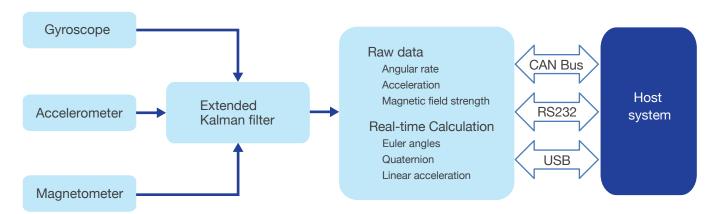
Key Features

- MEMS-based 9-axis inertial measurement unit (IMU) with on-board sensor fusion
- Very low-noise gyroscope for low-drift measurements with a bias stability of 4°/hour
- Dual gyroscope mode with additional high-range gyroscope for measurements above 400°/s up to 2000°/s
- Real-time, on-device calculation of sensor orientation and linear acceleration
- CAN bus (partial CANopen support) or RS232 communication interface options. All models include a USB connection.
- IP67 rated housing (dustproof and waterproof)
- Versatile software and library support for data acquisition and sensor configuration

Potential Applications

- Robotic manipulator forward kinematics control
- Automotive dead reckoning
- Object orientation tracking for VR/AR
- Automatic guided vehicle (AGV) navigation

Web: https://www.lp-research.com



NOTE: Diagram is simplified. Please ask us, if you need more detailed information.

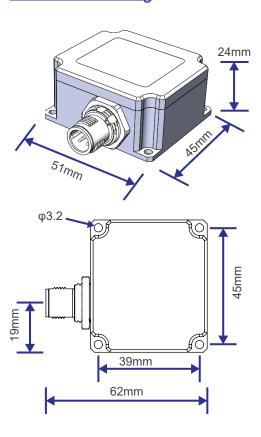


Sensor Specifications

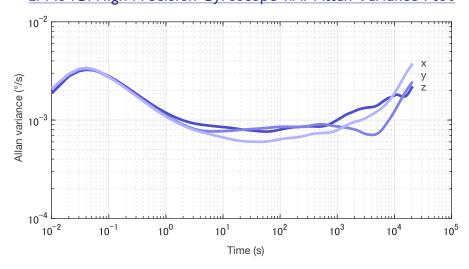
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|------------------------------|--|-----------------|
| Product name | LPMS-IG1 CAN | LPMS-IG1 RS232 |
| Wired interface | CAN Bus, USB | RS232, USB |
| Baudrate | 1M bit/s | 921600 bit/s |
| Communication protocol | LP-CAN / CANopen | LP-BUS |
| Size | 51 x 45 x 24 mm | |
| Weight | 76 g | |
| Orientation range | Roll: ±180°; Pitch: ±90°; Yaw: ±180° | |
| Orientation resolution | 0.01° | |
| Accelerometer | 3-axis, ±2 / ± 4 / ± 8 / ± 16 g, 16 bits | |
| Gyroscope | Dual gyroscope design: #1: 3-axis, \pm 400, 24 bits #2: 3-axis, \pm 1000 / \pm 2000 dps, 16 bits | |
| Static orientation stability | #1: 4 °/hour, #2: 6 °/hour | |
| Gyroscope noise density | #1: 0.002 dps/√Hz, #2: 0.004 dps/√Hz | |
| Magnetometer | 3-axis, ±2 / ±8 gauss, 16 bits | |
| Data output format | Raw data / Euler angle / Quaternion | |
| Data output rate | 5 ~ 500 Hz | |
| Power consumption | ≤400 mW @12 V | |
| Power supply | 5 V ~ 24 V DC | |
| Connector | Signal connector: M12 | |
| Housing | Aluminum, IP67 rated | |
| Temperature range | -20 ~ +80°C | |

NOTE: For detailed specifications, please refer to our product manuals.

Mechanical Drawing



LPMS-IG1 High Precision Gyroscope (#1) Allan Variance Plot



Package Contents

- LPMS-IG1 sensor x 1
- User guide card x 1
- Cable (incl. USB connector) x 1
- Box x 1
- Warranty (1 year)